

Doubly Decomposing Nonparametric Tensor Regression (ICML 2016)

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Outline

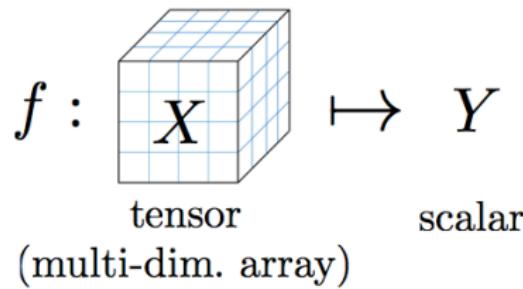
- Topic

- Nonparametric Regression with Tensor input

- Model

$$Y = f(X) + \epsilon$$

- Estimate (nonparametric) f



Outline

- **Method**

- Propose a **nonparametric model** with a Bayes estimator
- Improve its performance by controlling **bias and variance trade-off**

1 Tensor regression problem

2 Motivation

3 Our Approach

4 Convergence Analysis

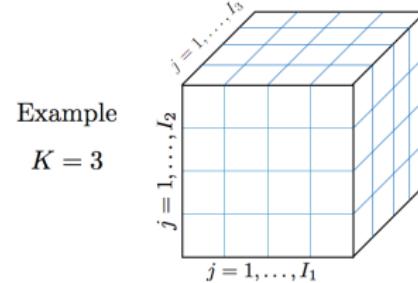
5 Experiments

6 Summary

Tensor Regression Problem

- Tensor data

- $X \in \mathbb{R}^{I_1 \times \dots \times I_K}$
- K : mode of tensor X
- I_k : dim of k -th mode



- Tensor Regression

- n observations $D_n = \{(X_i, Y_i)\}_{i=1}^n$
- Input (tensor) : $X_i \in \mathbb{R}^{I_1 \times \dots \times I_K}$ Output (scalar) : $Y_i \in \mathbb{R}$
- D_n is generated with a function $f : \mathbb{R}^{I_1 \times \dots \times I_K} \rightarrow \mathbb{R}$ as

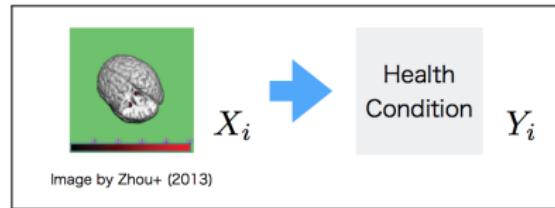
$$Y_i = f(X_i) + \epsilon_i$$

for $i = 1, \dots, n$

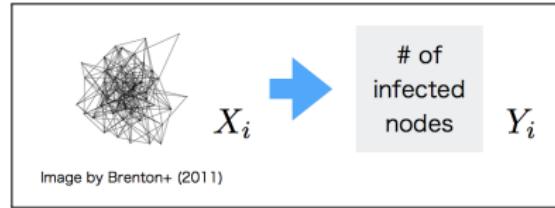
- ϵ_i is a Gaussian noise

Application of Tensor Regression Problem

- Predict health conditions from medical 3D images
 - X_i : medical 3D image of patient i , Y_i : health condition of i



- Predict spread of epidemics on networks
 - X_i : adjacency matrix of network i , Y_i : # of infected nodes



Related researches

- **Tensor linear regression**

$$Y = \langle W, X \rangle + \epsilon$$

- $W \in \mathbb{R}^{I_1 \times \dots \times I_K}$ is a parameter tensor
- Dyrholm et al. (2007); Zhou et al. (2013); Suzuki (2015); Guhaniyogi et al. (2015),etc...

- **Nonparametric tensor regression**

$$Y = f(X) + \epsilon$$

- $f : X \mapsto Y$ is possibly nonlinear function
- Zhao et al. (2014); Hou et al. (2015),etc...

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Motivation

- **Interest** : Convergence of an estimator \hat{f}_n

$$E\|\hat{f}_n - f^*\|^2 = O\left(n^{-?}\right)$$

- n : # of observations
- \hat{f}_n : estimator
- f^* : target
- Take the nonparametric approach to reduce bias

Motivation

- **Starting point** : the (naive) nonparametric approach

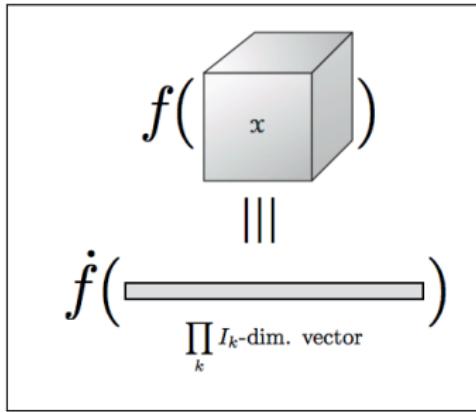
$$\min_{f \in \mathcal{F}} E_n [\ell(Y, f(X))] , \quad \ell : \text{loss function}$$

- $\mathcal{F} := \{f : \mathbb{R}^{I_1 \times \dots \times I_K} \rightarrow \mathbb{R} | f \text{ is } \beta\text{-smooth}\}$
- Let \mathcal{F} be a hypothesis set

- **Problem** : the curse of dimensionality
 - An estimator by this approach has quite slow convergence

The curse of dimensionality

- Performance of the estimator of f gets worse with tensor input



Naive estimator \tilde{f}_n

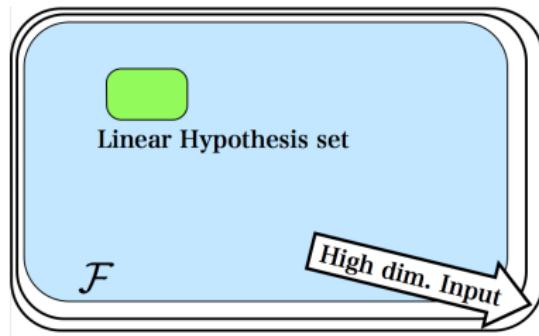
$$\|\tilde{f}_n - f^*\|^2 = O\left(n^{-2\beta/(2\beta + \prod_k I_k)}\right),$$

where β is smoothness of f .

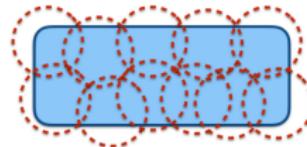
- $\prod_k I_k = \#$ of elements in X

Why the curse exists?

- The hypothesis set \mathcal{F} is **quite complex** (large) due to high dimensionality of X



Metric entropy via ϵ -nets
(measure complexity)

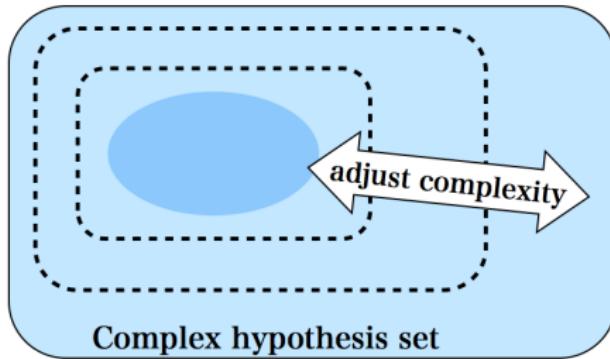


- Complex hypothesis sets make variance of estimators larger



Our idea

- **Reduce redundancy of hypotheses**
 - Data and models are often redundant
 - Represent X and f by less complex elements



Example of reduction

1. Low-rank approx. of matrix
 2. LASSO
- ...

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Double Decomposition

- **Outline of Double Decomposition**

- ➊ Decompose input $X \in \mathbb{R}^{I_1 \times \dots \times I_K}$
- ➋ Decompose function $f \in \mathcal{F}$

Input Tensor
Decomposition

$$f(x) = f(\text{cube}) = f(\text{---} + \text{---} + \dots)$$

Functional
Decomposition

$$f(\text{---}) = \sum_m f_m^{(1)}(\parallel) f_m^{(2)}(\perp) f_m^{(3)}(\diagup)$$

Double Decomposition 1

- **1. Tensor (CP) Decomposition**

- Consider $X \in \mathbb{R}^{I_1 \times \dots \times I_K}$
- There exists a set of normalized vectors $\{x_r^{(k)} \in \mathbb{R}^{I_k}\}_{r,k=1,1}^{R^*,K}$ and scale term λ_r for all $r = 1, \dots, R^*$, then

$$X = \sum_{r=1}^{R^*} \lambda_r x_r^{(1)} \otimes x_r^{(2)} \otimes \dots \otimes x_r^{(K)}.$$

- R^* is a tensor rank

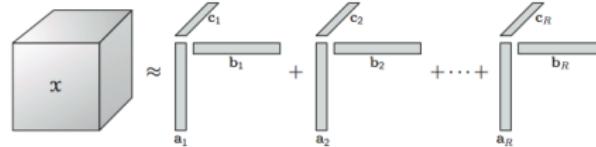


Image by Kolda+ (2009)

Double Decomposition 2

• 2. Functional Decomposition

- For each r , consider a function $f(x_r^{(1)}, x_r^{(2)}, \dots, x_r^{(K)})$
 - $x_r^{(k)}$ are I_k -dimensional vectors
- There exist $M^* \in \mathbb{Z}_+ \cup \{\infty\}$ and a set of local functions $\{f_m^{(k)}\}_{k,m=1}^{K,M^*}$ satisfying

$$f(x_r^{(1)}, x_r^{(2)}, \dots, x_r^{(K)}) = \sum_{m=1}^{M^*} \prod_{k=1}^K f_m^{(k)}(x_r^{(k)}).$$

- M^* is a model complexity

Proposed Framework

- Assumption
 - f is additive separable with respect to $r = 1, \dots, R^*$
- Consider doubly decomposed form of f

$$f(X) = \sum_{m=1}^{M^*} \sum_{r=1}^{R^*} \lambda_r \prod_{k=1}^K f_m^{(k)}(x_r^{(k)})$$

- **Additive-Multiplicative Nonparametric Regression (AMNR)**

- Represent $f(X)$ by $f_m^{(k)}$ with a **low-dimensional (I_k -dim.) vector as input**
- M^* (model complexity) and R^* (tensor rank) are tuning parameters

Proposed Framework

- **Our approach**

$$\min_{f \in \mathcal{G}} E_n [\ell(Y, f(X))]$$

- $\mathcal{G} := \left\{ f : \mathbb{R}^{I_1 \times \dots \times I_K} \rightarrow \mathbb{R} \mid f \text{ is AMNR, } f_m^{(k)} \text{ are } \beta\text{-smooth} \right\}$

- **Expected advantage**

- \mathcal{G} can be a **less complex** hypothesis set than \mathcal{F} by tuning M^*
 - By calculating the metric entropy
- \mathcal{G} does not increase bias a few

Estimation Method

- The Bayes method with the Gaussian process prior.
- Prior

$$\pi(f) = \prod_m \prod_k \mathcal{GP}^{(k)}(f_m^{(k)}),$$

- Posterior

$$\pi(f|D_n) = \frac{\exp(-\sum_{i=1}^n (Y_i - G[f](X_i))^2)}{\int \exp(-\sum_{i=1}^n (Y_i - G[f'](X_i))^2) \pi(df')} \pi(f),$$

$$\text{where } G[f](X_i) := \sum_{m=1}^{M^*} \sum_{r=1}^{R^*} \prod_{k=1}^K f_m^{(k)} \left(x_{r,i}^{(k)} \right).$$

- Implementation
 - The estimation bases on Gibbs sampling

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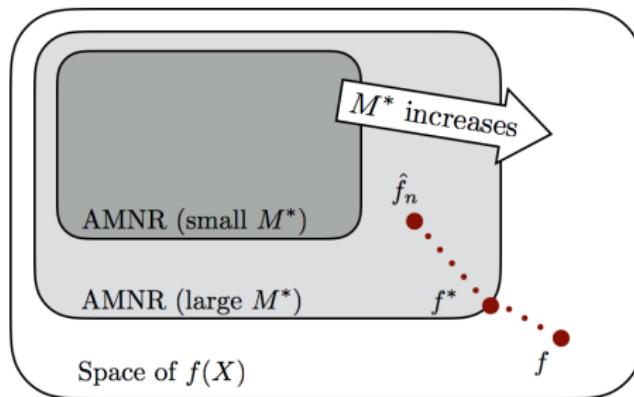
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Analyze Convergence Theoretically

- In the form of AMNR, M^* controls the size of bias
 - As M^* increases, the bias decreases



- Focus on the distance between \hat{f}_n and f^* with given M^*
 - We start with a case then finite M^* is sufficient to represent f
 - Then, we consider M^* is larger (infinite)

Finite M^* Case

- In the following, we assume that
 - i True $f_m^{(k)}$ belongs to Sobolev space with order β
 - ii Parameters of the prior estimation is appropriately selected

Theorem 1

Let $M^* < \infty$. Then, with some finite constant $C > 0$,

$$E\|\hat{f}_n - f^*\|_n^2 \leq Cn^{-2\beta/(2\beta + \max_k I_k)}.$$

- Remind that the naive nonparametric estimator \tilde{f}_n has a convergence rate $n^{-2\beta/(2\beta + \prod_k I_k)}$

Infinite M^* Case

- With infinite M^* , we estimate first M components with some assumption.

Theorem 2

Assume that with some constant $\gamma \geq 1$,

$\left\| \sum_r \lambda_r \prod_k f_m^{(k)} \right\|_2 = o(m^{-\gamma-1})$, as $m \rightarrow \infty$. Suppose we construct the estimator with a proximal complexity M such that

$$M \asymp (n^{2\beta/(2\beta + \max_k I_k)})^{1/(1+\gamma)}.$$

Then, with some finite constant $C > 0$,

$$E\|\hat{f}_n - f^*\|_n^2 \leq C(n^{-2\beta/(2\beta + \max_k I_k)})^{\gamma/(1+\gamma)}.$$

Convergence Rate

- Compare Nonparametric method for Tensor Regression
 - For example case, we set $K = 3, I_k = 100, \beta = \gamma = 2$

Method	Convergence Rate	Example
Naive	$n^{-2\beta/(2\beta + \prod_k I_k)}$	$n^{-1/2501}$
AMNR (Finite M^*)	$n^{-2\beta/(2\beta + \max_k I_k)}$	$n^{-1/26}$
AMNR (Infinite M^*)	$(n^{-2\beta/(2\beta + \max_k I_k)})^{\gamma/(1+\gamma)}$	$n^{-1/39}$

- AMNR achieves better convergence rate, by reducing the size of the model space by the double decomposition

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Experiment Outline

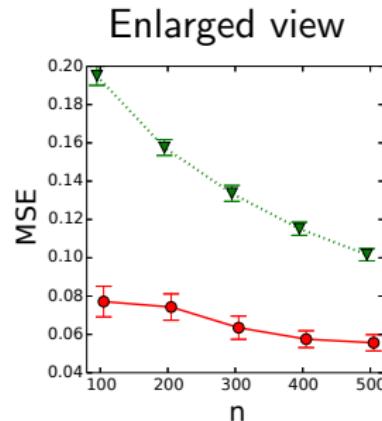
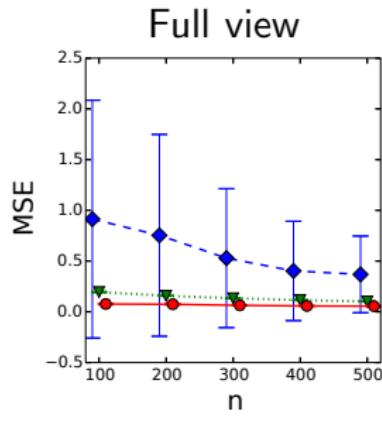
- We introduce 3 experiments
 - 1 Prediction performance
 - 2 Convergence analysis
 - 3 Real data analysis
- Methods
 - AMNR (our method)
 - TGP (Tensor Gaussian Process)
 - Close to the naive nonparametric estimator
 - TLR (Tensor Linear Regression)
 - Not nonparametric method

Prediction Performance

- Generate synthetic data with low rank tensor as

$$f(X) = \sum_{r=1}^2 \lambda_r \prod_{k=1}^K (1 + \exp(-\gamma^T x_r^{(k)}))^{-1}$$

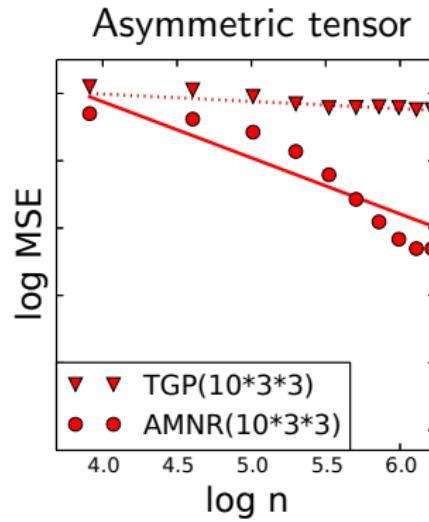
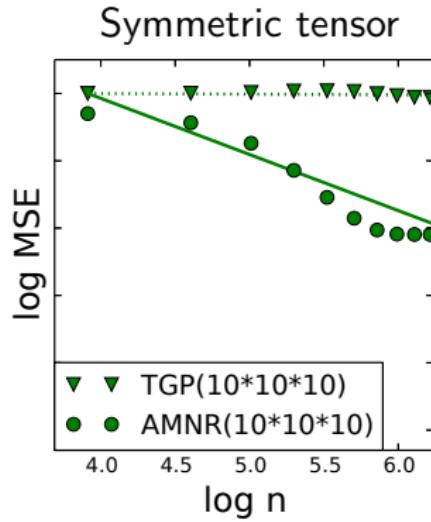
TLR	AMNR	TGP
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Convergence analysis

- Generate synthetic data with smoothness-controlled process

$$f(X) = \sum_{r=1}^R \prod_{k=1}^K \sum_l \mu_l \phi_l(\gamma^T x)$$

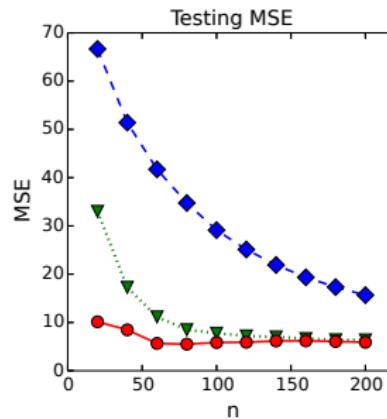


Real Data Analysis

- Epidemic Spreading Data

- X_i : Adjacency matrix of network i
- Y_i : the number of total infected nodes of network i

TLR AMNR TGP



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Conclusion

- Summary
 - Proposed nonparametric regression model with tensor input
 - Doubly decomposition controls the hypothesis complexity
 - The control reduces the variance of the estimator
- Future work
 - Computational complexity / convergence
 - Tuning parameters (β, γ) selection
 - Measure bias size

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