# Linear time algorithms for geodesic problems on simple polygons. 



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## THE PROBLEM



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## INTRODUCTION



- Geodesic: shortest path that stays within $P$
- Always exists and is unique
- Geodesic distance: sum of lengths of the segments


## DIAMETER AND RADIUS



- Diameter (diametral pair): largest geodesic distance
- Radius (center): smallest distance to farthest neighbor


## KNOWN RESULTS

| Polygon | Diameter | Radius / Center | Farthest Voronoi |
| :---: | :---: | :---: | :---: |
| Simple | $\mathrm{O}(\mathrm{n})$ [HS'93] | $O(n \log n)$ <br> [PSR'89] | $\begin{gathered} O((n+m) \log (n+m)) \\ {[\text { AFW' } 93]} \end{gathered}$ |

- All problems have been heavily studied in simple polygons
- Only the diameter problem matches the lower bound
- Several results with other metrics in recent years, but no progress in these problems


## OUR RESULTS

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## COMPUTING THE CENTER



## CENTER DEFINITION



Let $F(p)=\max \{d(p, q)\}$ for all $q$ in $P$

- The center minimizes $F(p)$
- Location is (often) unrelated to the diameter


## NAIVE ALGORITHM



- Center may be an interior point of $P$
- Its farthest neighbors are vertices (at most 3 in general position)
- Vertex of the (geodesic) farthest Voronoi
- $\mathrm{O}\left(\mathrm{n}^{3}\right)$ candidates
- Verifying in polynomial time also possible


## EFFICIENT ALGORITHM'89



Chord-oracle query

- Given a chord of P, determines which side contains c
- Runs in $\mathrm{O}(\mathrm{n})$ time


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- Binary search to narrow the search to a triangle
- Use optimization tricks to find the center
- No pruning possible -> $\Theta$ (n log n) time


## APEXEDTRIANGLES



- Encodes distance to a potential farthest neighbor $v$
- All points in the triangle have (topologically equivalent) paths to $v$
- Simple (quadratic) function to encode distance
- We ignore P and work on the triangles


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## OUR APPROACH



- Cover P with apexed triangles that encode F(p)
- Ignore P
- Use cuttings to prune the triangles and recurse


## DIFFICULTIES

Which triangles do we use?

- A vertex can generate $\Theta(n)$ apexed triangles
- Many triangles are irrelevant
- Use geometric observations to avoid them


## DETERMINING RELEVANTTRIANGLES



For each vertex compute its farthest neighbor

## DETERMINING RELEVANTTRIANGLES



We can compute the farthest neighbor of each vertex in total $O(n)$ time.

## DETERMINING RELEVANTTRIANGLES


$v$ is marked if $v$ is farthest neighbor of some other vertex

## MARKED VERTICES


-For all marked vertex we construct its funnel F(v)

- Funnel contains furthest vertices (and two additional neighbors)

Lemma $\mathrm{FV}(\mathrm{v}) \subseteq F(\mathrm{v})$ for any marked vertex v

## MARKED VERTICES



## MARKED VERTICES



## UNMARKED VERTICES



## UNMARKEDVERTICES



- Two adjacent $u, v$ such that $f(u) \neq f(v)$ define an Hourglass $H(v)$
- Upper chain may contain unmarked vertices


# PROPERTIES OFTHE DECOMPOSITION 

## Lemma This decomposition is great!

- All hourglasses and funnels have overall linear complexity
- Computed in linear time
- Linear space
- Covers P
- Each point and its farthest neighbor are in an hourglass/funnel

- Vertices (except endpoints) share farthest neighbor
- Want to encode distance to it


## DECOMPOSING A FUNNEL



- Look for topologically equivalent shortest paths
- Similar paths fall in the same apexed triangle


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## DECOMPOSING A FUNNEL



- For each triangle we define an apexed function
- $f(p)=d(p, a)+d(a, v)$


## HOURGLASSES



- We decompose into triangles (similar to funnel)
- The number of triangles is linear on the size of the hourglass
LET'S RECAP

- Two step decomposition.
- Compute a covering of $P$
- Further cover regions with triangles
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- Overall O(n) triangles
- For any point, there is a triangle containing him
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## LET'S RECAP



We ignore $P$ and use prune\&search on triangles

## PRUNE AND SEARCH



- Covered P with $\mathrm{O}(\mathrm{n})$ triangles
- Each triangle associated with a distance function
- We ignore P and work on the triangles


## CUTTINGS



- We construct a cutting of the triangles chords (sides)
- Partition into O(1) cells
- Each cell intersecting the boundary of at most $\varepsilon n$ triangles


## PRUNE AND SEARCH



- Use the chord oracle of Pollack-Sharir-Rote
- Reduce the problem to a sub-cell
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## SUMMARY

- Cover P with funnels/hourglasses
- Further cover the regions with triangles
- Ignore $P$ and apply prune and search to triangles
- Finish a triangular region
- Can be solved in linear time using cuttings in $\mathbf{R}^{\mathbf{3}}$


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Theorem We can compute the center of a simple polygon in linear time

## OPEN QUESTIONS

- Can we compute the center of a set of sites $S$ in the interior of the polygon in linear time?

| Polygon | Diameter | Center |
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| Simple | $\mathrm{O}(\mathrm{n})\left[\mathrm{HS} \mathrm{S}^{\prime} 93\right]$ | $\mathbf{O ( n )}\left[\mathbf{A B B C K O} \mathbf{O}^{\prime} 15\right]$ |
| General | $\mathrm{O}\left(\mathrm{n}^{7.73}\right)\left[B K O^{\prime} 10\right]$ | $\mathrm{O}\left(\mathrm{n}^{12+\varepsilon}\right)\left[\mathrm{BKO} \mathrm{O}^{\prime} 14\right]$ |

- For the case of polygonal domains (polygons with holes), the running times are polynomial but unfeasible. Can we improve them? What about lower bounds?


## QUESTIONS? COMMENTS?

Thanks for your attention!

## Summary

| Polygon | Diameter | Radius / Center | Farthest Voronoi | Closest Voronoi |
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